

# Eli LeChien

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## Education

<b>Stanford University</b> – Palo Alto, CA	<i>Expected Graduation: March 2026</i>
M.S. in Electrical Engineering	<i>GPA: 4.00</i>
<b>Purdue University</b> – West Lafayette, IN	<i>Aug 2020–May 2024</i>
B.S. in Electrical Engineering	<i>GPA: 4.00</i>

## Skills

**Software:** KiCad, LTSpice, ANSYS, C/C++, MATLAB, Python, Convex Optimization/CVXPY, Machine Learning

**Hardware:** Analog circuit design, PCB design, power electronics, microcontrollers, motors, 3D printers, sensors

## Work Experience

<b>Stanford Robotics Center Smart Sensing Systems Lab</b> , <i>Research Assistant</i> – Palo Alto, CA	<i>Sept 2024 – Present</i>
<ul style="list-style-type: none"><li>Designed PCB to characterize resistors and capacitors under 100 atm pressure with .1% sensor resolution</li><li>Designed electromechanical buoyancy management system for a drone-deployable 300g ocean profiler.</li><li>Aligned with Oceanographers to specify sensor characteristics to reliably capture data in 0-1km depth.</li></ul>	
<b>FANUC</b> , <i>Product Management Intern</i> – Palo Alto, CA	<i>Sept 2024 – Dec 2024</i>
<ul style="list-style-type: none"><li>Researched new product opportunities in the high-mix weld shop collaborative robotics space, including 50+ interviews conducted across end users, distributors, integrators, competitors, and FANUC sales.</li></ul>	
<b>Tesla</b> , <i>Drive Systems Design Intern</i> – Palo Alto, CA	<i>May 2024 – Sept 2024</i>
<ul style="list-style-type: none"><li>Developed code library to integrate new meshing software into motor optimization tool, allowing for 200+ additional mesh settings to improve simulation accuracy and resulting in a 30% runtime decrease.</li><li>Worked cross-functionally with Tesla bot team to improve modeling of robotic actuators and developed a new meshing method yielding better simulation accuracy and 99% pure cogging torque waveforms.</li><li>Assisted with construction of prototype motors, including magnetization of a novel rotor with a 3T field.</li></ul>	
<b>Purdue Electric Vehicle Lab</b> , <i>Research Assistant</i> – West Lafayette, IN	<i>Jan 2022 – May 2024</i>
<ul style="list-style-type: none"><li>Developed power electronics control system for 230kW in-motion wireless charging of electric semi-trucks.</li><li>Designed and soldered 6-layer mixed-signal PCB for microcontroller peripherals totaling 182 components.</li><li>Created a fiber optic magnetic field synchronization protocol for transmitter coils, achieving a &lt;11 <math>\mu</math>s delay.</li></ul>	
<b>Tesla</b> , <i>Drive Unit Production Controls Intern</i> – Austin, TX	<i>May 2022 – Dec 2022</i>
<ul style="list-style-type: none"><li>Made continuous process improvements while balancing stakeholders in production, maintenance, engineering, and management, yielding ~250 code commits across multiple production lines.</li><li>Managed implementation of statistical process control on 50+ stations, enabling parameter drift detection.</li></ul>	

## Leadership Activities

<b>Stanford Linear Circuit Analysis Course (EE101A)</b> , <i>Course Assistant</i>	<i>Sept 2024 – Dec 2024</i>
<ul style="list-style-type: none"><li>Guided 60+ students in lab sections and office hours, improving comprehension and problem-solving skills.</li></ul>	
<b>Purdue Engineering Student Council</b> , <i>Website Manager &amp; Committee Member</i>	<i>Aug 2021 – May 2024</i>
<ul style="list-style-type: none"><li>Redesigned website to be more informative and intuitive to recruiters from 400+ companies.</li><li>Selected and interviewed members of 40 multidisciplinary organizations to allocate \$25K in funding.</li></ul>	
<b>Senior Design Cummins Electric Semi Team</b> , <i>Team Lead</i>	<i>Aug 2023 – Dec 2023</i>
<ul style="list-style-type: none"><li>Managed team designing vehicle hardware and power controls for wireless charging of electric semi-trucks through task delegation, timeline dictation, and allocation of a budget of \$10k for a 230kW power system.</li></ul>	